Math2121 (Spring 2012-2013)

Tutorial Note 3

Linear Transformations

- Key Questions -

- What are linear transformations? (see page 1 of note 4)
- How to obtain a matrix of a linear transformation from \mathbb{R}^n to \mathbb{R}^m ?

Problem 1. In tutorial note 2 we know that C[0,1] is a vector space with naturally defined addition and scalar multiplication. Show that $T : C[0,1] \rightarrow C[0,1]$ defined by

$$(Tf)(x) = \int_0^x f(t) dt$$

is linear. Moreover, find all the solution of Tf = 0. i.e., what is $\{f \in C[0,1] : Tf = 0\}$?

Solution.

Problem 2.

- (a) Find a matrix R_{θ} that rotates a point $p \in \mathbb{R}^2$ by an angle θ counter-closckwise about the origin.
- (b) Also find a matrix *B* that reflects a point along the diagonal y = x.
- (c) Finally, find one that reflects a point along the line $y = \tan \alpha x$, where $\alpha \in [0, \pi/2]$.

Solution.

Problem 3. Determine which of the following maps are linear transformations.

- (a) The transformation *T* defined by $T(x_1, x_2)^T = (2x_1 3x_2, x_1 + 4, 5x_2)^T$.
- (b) The transformation *T* defined by $T(x_1, x_2)^T = (4x_1 2x_2, 3|x_2|)^T$.
- (c) The transformation T defined by $T(x_1, x_2, x_3)^T = (1, x_2, x_3)^T$.
- (d) The transformation T defined by $T(x_1, x_2, x_3)^T = (x_1, 0, x_3)^T$.
- (e) The transformation T defined by $T(x_1, x_2, x_3)^T = (x_1, x_2, -x_3)^T$.

Solution.

Problem 4. Let $T : \mathbb{R}^n \to \mathbb{R}^m$ be a linear transformation. Determine whether or not *T* is one-to-one in each of the following situations:

 (\mathbf{a}) When n > m.

 (\mathbf{b}) When n = m.

 (\mathbf{c}) When n < m.

Fill the symbols A, B and C in _____ defined below:

A *T* is a one-to-one transformation.

B T is not a one-to-one transformation.

C There is not enough information to tell.

Solution.

Problem 5. Let $T : \mathbb{R}^n \to \mathbb{R}^m$ be a linear transformation. Let *A* be the standard matrix of *T*.

Fill the correct symbols A, B and C in _____ for each of the following situations.

(a) If every row in the row echelon form of A has a pivot.

(**b**) If the row echelon form of *A* has a row of zeros.

(c) If two rows in the row echelon form of A do not have pivots.

(d) If the row echelon form of *A* has a pivot in every column.

Where:

B T is onto.

 $\boxed{\mathbf{C}}$ there is not enough information to tell.

Solution.